

Measuring sets in infinite groups

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ABSTRACT. We are now witnessing a rapid growth of a new part of group theory which has become known as “statistical group theory”. A typical result in this area would say something like “a random element (or a tuple of elements) of a group G has a property P with probability p ”. The validity of a statement like that does, of course, heavily depend on how one defines probability on groups, or, equivalently, how one measures sets in a group (in particular, in a free group). We hope that new approaches to defining probabilities on groups outlined in this paper create, among other things, an appropriate framework for the study of the “average case” complexity of algorithms on groups.

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1. Introduction

A new part of group theory, often called “statistical group theory”, is becoming increasingly popular since it connects group theory to other areas of science, most of all to statistics and to theoretical computer science.

A typical result in this area would say something like “a random element (or a tuple of elements) of a group G has a property P with probability p ” (see e.g. [1], [5], [19]). The validity of a statement like that does, of course, heavily depend on

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how one defines probability on groups, or, equivalently, how one measures sets in a group. This is the problem that we address in the present paper; we feel that it deserves some discussion at a general methodological level. A much more technical development of some of the ideas can be found in [3].

Our approach to statistical group theory is formed by needs of practical computations with infinite groups. In particular, the starting point of our study of measures on groups was the desire to identify measures which can be used in the analysis of the behaviour of genetic algorithms on infinite groups [16, 17, 23]. Hence one of our main requirements for a measure is that it reflects the nature of algorithms used for generating random or pseudo-random elements of a group. In Section 2 we discuss some other natural conditions which would make a measure suitable for practical computations.

Since we focus mostly on finitely generated discrete groups, almost all measures defined in the present paper are *atomic*. Recall that a probabilistic measure on a countable set is atomic if every subset is measurable. Clearly, the latter condition is natural in the context of computational group theory where we are restricted to dealing with finite sets of elements. In Section 3, we suggest a simple (perhaps even naive) general approach to constructing atomic measures on countable groups associated with various length (or “complexity”) functions.

In Sections 4, 5, we look at the problem of measuring sets in infinite groups when pseudorandom elements of a group are generated by a deterministic process. This naturally leads to Kolmogorov complexity of words as a more adequate concept of the “length function” on a free group. The invariance theorems for Kolmogorov complexity provide for a uniform treatment of different ways to define computational complexity functions on groups. We note that in [10], Grigorchuk discovered some interesting relations between Kolmogorov’s complexity of the word problem and growth of groups.

Section 6 deals with the so-called *short elements bias* which occurs in any generator of random elements of a group G with a given atomic probability distribution μ . This effect is based on a simple observation that the measure $\mu(S)$ of an infinite set $S \subset G$ is essentially defined by a few short elements from S . There are several principal approaches to this problem. The most popular one suggests to consider relative frequencies

$$\rho_k(S) = \frac{|S \cap B_k|}{|B_k|}$$

(where B_k is the ball of radius k in the Cayley graph of G with respect to a given set of generators) and their behaviour at “infinity” when $k \rightarrow \infty$. This leads to the notion of *asymptotic density* of S defined as the following limit (if it exists):

$$\rho(S) = \lim_{k \rightarrow \infty} \frac{|S \cap B_k|}{|B_k|}.$$

Another way to avoid the short elements bias is to replace a single measure μ on G by a parametric family of distributions $\{\mu_L\}$ in which L is the average length of elements of G relative to μ_L . In this case the asymptotic behaviour of the set S is described by the limit

$$\mu_\infty(S) = \lim_{L \rightarrow \infty} \mu_L(S).$$

We discuss asymptotic densities in the last section and refer to [3] for a detailed discussion of the second method.

In Section 7, we show how a specific choice of the probability distribution on a free group allows one to introduce degrees of polynomial growth “on average” for functions on groups. In particular, it is a possible way for introducing hierarchies of the *average case complexity* of various algorithms for infinite groups, making meaningful statements like “the algorithm works in cubic time on average”.

Section 8 discusses probability measures generated by random walks on the Cayley graph of a free group F_n . This class of measures is well suited for analysis of randomized algorithms on groups and behaves nicely with respect to taking finite factor groups.

In Section 10, we analyze some limitations of the asymptotic density as a tool for measuring sets in infinite groups. The most important one is that it is not sensitive enough, i.e., many sets of intuitively different sizes have the same asymptotic density (usually 1 or 0). Indeed, in [27], Woess proved that every normal subgroup of infinite index in a free group F_n , $n \geq 2$, has asymptotic density 0.

Another disappointment is offered by Theorem 10.4 which states that the set of primitive elements of a free group F_n , $n \geq 2$, has asymptotic density 0. In fact, our proof provides lower and upper bounds for the relative frequencies of the set of primitive elements of F_n , which is a result of independent interest.

One way around this problem is to consider the so-called *growth rate* of the relative frequency defined by

$$\gamma(S) = \limsup_{k \rightarrow \infty} \sqrt[k]{\rho_k(S)}.$$

This is a useful characteristic of growth of the set S and it is more sensitive than the asymptotic density $\rho(S)$ (see Section 10.2).

On the other hand, the function $\gamma(S)$ is not even additive, which makes it difficult to use as a measuring tool.

It would be very interesting to check whether sets having the same asymptotic densities (see, for example, [1], [5], [19]) will show different sizes with respect to a more sensitive and adequate measure.

2. Conditions on a measure

Let G be a group (finite or countable infinite). A probabilistic measure μ on G has to satisfy the standard axioms of a probability space.

Recall that a probability space is a set X together with a σ -algebra of subsets \mathcal{A} of X and a probability measure $\mu : \mathcal{A} \rightarrow \mathbb{R}$ which is a real-valued function satisfying the following axioms:

(M1) For any set $S \subseteq \mathcal{A}$, $\mu(S) \geq 0$.

(M2) $\mu(X) = 1$.

(M3) If $S_i, i \in I$, is a countable collection of pairwise disjoint sets from \mathcal{A} , then

$$\mu \left(\bigcup_{i \in I} S_i \right) = \sum_{i \in I} \mu(S_i).$$

Analysis of behaviour of randomized algorithms on groups requires estimation of the probability of a given element. A measure μ on X is *atomic* if it satisfies the following condition

(M4) X is countable and every subset $S \subseteq X$ is μ -measurable.

In this paper, we shall consider mostly atomic measures on a free group F_n of rank n with basis $\{x_1, \dots, x_n\}$. Note that since every coset with respect to a subgroup $H < F_n$ is measurable, this defines an induced measure on the factor set F_n/H ; this new induced measure is also atomic.

A question that might arise (and which is usually addressed in the theory of growth of groups) is whether or not a measure should depend on a particular basis of F_n . Independence of a basis means invariance of the measure under the action of $\text{Aut } F_n$. In the case of atomic measures, this implies that infinitely many singletons $\{g^h\}$, $h \in F_n$, have the same measure as $\{g\}$ does, which implies $\mu(g) = 0$. Hence the only $(\text{Aut } F_n)$ -invariant atomic measure on F_n is the singular measure concentrated at the origin 1, and atomic measures necessarily depend on the choice of a basis in F_n .

Finally, we record several informal conditions on a measure which will guide us in evaluating behaviour of various measures:

- (C1) a measure should be natural, i.e., it should meet our expectations of what the sizes of various sets in a group are.
- (C2) a measure should be sensitive, i.e., sets that (intuitively) seem to be of different sizes, should have different measures.
- (C3) $\mu(S)$ (or, at least, rather tight bounds for $\mu(S)$) should be easily computable for “natural” sets $S \subseteq F_n$.
- (C4) a measure should admit a natural generator of random elements in the group.

In the rest of the paper we consider various approaches to constructing measures on groups, checking them against our list of conditions (C1)–(C4).

3. Atomic probability measures

In this section, we discuss a general method which allows one to define atomic probabilistic measures on countable groups. Our definition of a measure is based on a notion of “complexity” of elements of G and a probability distribution on the set of all non-negative integers \mathcal{N} . These are the initial basic objects which determine the intrinsic behaviour of the corresponding measure.

Depending on a problem at hand, one can use different types of complexities, for example, it can be a descriptive complexity, a computational complexity, the minimal length of the word representing an element with respect to a given generating set, or the length of the normal form of an element. In general, a *complexity function* (or a *complexity*) on a group G is an arbitrary non-negative integral function $c : G \rightarrow \mathcal{N}$ such that for every $n \in \mathcal{N}$ the preimage $c^{-1}(n)$ is a finite subset of G . Note that a group G with a complexity function is countable. At the end of the section we discuss more general complexity functions which allow elements of G to have infinite complexity and elements with real value complexities (in this case the group G can be uncountable).

The most important example of a complexity function is the *length function* on a group. Let G be a finitely generated group with a given finite set of generators $S \subseteq G$. For an element $g \in G$ by $l_S(g)$ we denote the minimal non-negative integer n such that $g = y_1 \dots y_n$ for some $y_i \in S \cup S^{-1}$. If H is a subgroup of G then the restriction of l_S on H gives rise to a new complexity function on H , which might not be a length function on H .

In Section 4 we consider another important type of complexity functions on G , so-called Kolmogorov complexity functions.

For a given complexity function c on G and a discrete probability distribution on non-negative integers \mathcal{N} , given by a density function $d : \mathcal{N} \rightarrow R$, we are going to construct an atomic measure $\mu_{c,d}$ on G .

Recall that, for an atomic measure on a countable set X , the value of μ on an arbitrary subset $S \subset X$ is defined uniquely by the formula

$$(3.1) \quad \mu(S) = \sum_{w \in S} \mu(w).$$

This shows that an atomic measure μ is completely determined by its values on singletons $\{w\}$, $w \in X$. In other words, to define μ it suffices to define a function $p : X \rightarrow R$ (and put $\mu(w) = p(w)$), which is called a *probability mass function* or a *density function* on X , such that:

$$p(w) \geq 0 \quad \text{for all } w \in X,$$

$$\sum_{w \in X} p(w) = 1.$$

Now we put forward one more condition on the measure μ which ties μ to a complexity function $c : G \rightarrow \mathcal{N}$:

(C5) for any $u, v \in G$, $c(u) = c(v)$ implies $\mu(u) = \mu(v)$.

We call a measure μ on G *c-invariant* if μ satisfies (C5), i.e., elements of the same c -complexity have the same measure.

The following result describes c -invariant measures on G . For $k \in \mathcal{N}$ define the k -sphere C_k with respect to a complexity c as follows:

$$C_k = \{w \in G \mid c(w) = k\}.$$

Similarly, by B_n we denote the disc or the ball of radius n with respect to c :

$$B_n = \{w \in G \mid c(w) \leq n\}.$$

LEMMA 3.1. *Let μ be an atomic measure on G and c a complexity function on G . Then:*

(1) *If μ is c -invariant, then the function $d_\mu : \mathcal{N} \rightarrow R$ defined by*

$$d_\mu : k \rightarrow \mu(C_k)$$

is a probability measure on \mathcal{N} ;

(2) *if $d : \mathcal{N} \rightarrow R$ is a probability measure on \mathcal{N} , then the function $p_{c,d} : G \rightarrow R$ defined by*

$$p_{c,d}(w) = \frac{d(c(w))}{|C_n|}$$

is a probability function which gives rise to an atomic c -invariant measure on G .

Proof is obvious. □

REMARK 3.2. If $c(w)$ is the length of an element $w \in G$ with respect to a given finite set of generators of G , then c -invariant measures play an important role in asymptotic group theory. We will call such measures *homogeneous*.

Since $d(k) \rightarrow 0$ as $k \rightarrow \infty$, the following elementary but fundamental property of $\mu_{c,d}$ holds.

More complex (with respect to a given complexity c) elements of a set $S \subset X$ contribute less to $\mu_{c,d}(S)$.

This discussion shows that in defining the probability measures $\mu_{c,d}$ on G , everything boils down to the problem of choosing a complexity function $c : G \rightarrow \mathcal{N}$ and a moderating distribution $d : \mathcal{N} \rightarrow \mathbb{R}$. This choice might depend on a particular problem one would like to address. To that end, it seems reasonable to:

- (a) use complexity functions on G which reflect intrinsic features of the problem at hand;
- (b) use probability distributions on \mathcal{N} which reflect the nature of the process which generates (pseudo)random elements of the group, or which allow to study the statistical properties of the group in a meaningful and computationally feasible way.

We discuss possible complexity functions on groups in the next section. Here are some well-established parametric families of density functions on \mathcal{N} that we have considered in this framework:

(i) The *Poisson density*:

$$d_\lambda(k) = e^{-\lambda} \frac{\lambda^k}{k!}$$

(ii) The *exponential density*:

$$d_\lambda(k) = (1 - e^{-\lambda})e^{-\lambda k}$$

(iii) The *standard normal (Gauss) density*:

$$d_{a,\sigma}(k) = b \cdot e^{-\frac{(k-a)^2}{\sigma}}$$

(iv) The *Cauchy density*:

$$d_\lambda(k) = b \cdot \frac{1}{(k - \lambda)^2 + 1}$$

(v) The *Dirac density*:

$$d_m(k) = \begin{cases} 1 & \text{if } k = m \\ 0 & \text{if } k \neq m \end{cases}$$

The following density function depends on a given complexity function c on G :

(vi) The *finite disc uniform density*:

$$d_m(k) = \begin{cases} \frac{|C_k|}{|B_m|} & \text{if } k \leq m \\ 0 & \text{otherwise} \end{cases}$$

For example, the Cauchy density functions are very convenient for defining degrees of polynomial growth “on average”, while the exponential density functions are suitable for defining degrees of exponential growth “on average” (see Section 7).

On the other hand, different distributions arise from different random generators of elements in a group. For example, Dirac densities correspond to the uniform random generators on the spheres C_n ; finite disc densities arise from uniform random generators on the discs B_n . Measures on the free group F_n associated with the exponential moderating distribution on \mathcal{N} have especially nice properties and are studied in some detail in [3].

REMARK 3.3. Sometimes we allow for some elements in the set X to have infinite complexity ∞ . In this case we consider complexity functions of the type $c : X \rightarrow N \cup \{\infty\}$ such that $c^{-1}(n)$ is a finite subset of X for every integer n (so that we may have infinitely many elements in X with complexity ∞). Following our requirement that more complex elements contribute less to the measure, we define the probability density function p on X for elements with finite complexity, and for elements $x \in X$ of infinite complexity we just put $p(x) = 0$.

4. Kolmogorov complexity functions

4.1. Kolmogorov complexity functions on free groups. In this section we discuss complexity functions on free groups. We are going to represent elements of free groups as reduced words in a given basis, so the starting point of this discussion is complexity of *words*.

Let A be a finite alphabet and A^* the set of all finite words in A . The length $|w|$ of a word $w = x_1 \dots x_n$, $x_i \in A$, is equal to n . The length function $l : w \rightarrow |w|$ maps A^* into \mathcal{N} . Observe that $l^{-1}(n) = |A|^n$. It follows that

- The length function $l : A^* \rightarrow \mathcal{N}$ is a complexity function on A^* .

This is one of the basic complexity functions that we will consider in this paper. The problem however is that some very long words in A^* do not look very complex. For example, the word $a^{10^{100}}$, where $a \in A$, has length 10^{100} , but this word is very easy to describe. This leads to the notion of *Kolmogorov complexity*, or *descriptive complexity*, or sometimes it is called *algorithmic complexity*. We refer to [15], [26] for detailed treatment of Kolmogorov complexity.

Intuitively, Kolmogorov complexity of a word $w \in A^*$ is the minimum possible size (length) of a description of w with respect to a given formal general procedure. For example, one may think of the descriptive complexity of w as of the the minimum possible size of a program, in a given programming language, which produces w after finitely many steps. In this case, the word $a^{10^{100}}$ above will have complexity much less than 10^{100} .

Now we give a formal definition of Kolmogorov complexity.

It is sufficient to consider programs of a very particular type, say, Turing machines. Denote by $B = \{0, 1\}$ the standard binary alphabet and by B^* the set of all finite binary strings. Every Turing machine M determines a partial (perhaps empty) recursive function $f_M : B^* \rightarrow A^*$. The function f_M is defined on $x \in B^*$ if and only if the machine M starts on the tape with a word x , halts in finitely many steps, and a word $w \in A^*$ is written on the tape. In this event, $f_M(x) = w$. Denote by $s_M(x)$ and $t_M(x)$, respectively, the tape space and the number of steps needed for M to write w and halt.

The Kolmogorov complexity of a word $w \in A^*$ with respect to a given machine M is defined as follows:

$$K_M(w) = \begin{cases} \min\{|x| \mid x \in B^* \text{ \& } f_M(x) = w\} & \text{if such } x \text{ exists} \\ \infty & \text{otherwise} \end{cases}$$

Similarly, one can define *time bounded* and *space bounded* Kolmogorov complexities of a word $w \in A^*$. Namely, for a Turing machine M and a function

$$\beta : \mathcal{N} \rightarrow \mathcal{N}$$

(a *bound*) define the space bounded and time bounded Kolmogorov complexities $KS_M(x, \beta)$ and $KT_M(x, \beta)$ (with respect to the bound β) as follows:

$$KS_M(w, \beta) = \begin{cases} \min\{|x| \mid x \in B^* \ \& \ f_i(x) = w \ \& \ s_M(x) \leq \beta(|x|)\} & \text{if such } x \text{ exists} \\ \infty & \text{otherwise} \end{cases}$$

$$KT_M(w, \beta) = \begin{cases} \min\{|x| \mid x \in B^* \ \& \ f_i(x) = w \ \& \ t_M(x) \leq \beta(|x|)\} & \text{if such } x \text{ exists} \\ \infty & \text{otherwise} \end{cases}$$

These definitions depend on a given Turing machine M . It turns out that a *universal* Turing machine M provides an optimal notion of Kolmogorov complexity. Namely, the following invariance theorem holds.

Invariance Theorem I ([22] [14], [4]). *There exists a Turing machine U such that for any Turing machine M and for any word $w \in A^*$ the following inequality holds:*

$$K_U(w) \leq K_M(w) + C_M,$$

where C_M is a constant which does not depend on w .

Similar results hold for space bounded and time bounded Kolmogorov complexities.

Invariance Theorem II [12]. *There exists a Turing machine U such that for any Turing machine M , for any bound $\beta : \mathcal{N} \rightarrow \mathcal{N}$, and for any word $w \in A^*$ the following inequalities hold:*

$$KS_U(w, C_M \beta) \leq K_M(w, \beta) + C_M,$$

$$KT_U(w, C_M \beta \log(\beta)) \leq K_M(w, \beta) + C_M,$$

where C_M is a constant which does not depend on w .

The theorems above allow one to consider $K_U(w)$ as the Kolmogorov complexity $K(w)$ of a word $w \in A^*$, were U is an arbitrary fixed optimal machine.

We will use these different types of Kolmogorov complexities in constructing measures on a free group. But first, two remarks are in order (a bad news and a good news).

REMARK 4.1. The function $w \rightarrow K(w)$ is not recursive. Thus, we cannot effectively compute the Kolmogorov complexity of a given word. However, it turns out that we can estimate $K(w)$ by the length of w . This shows that the length $|w|$ as a complexity of w is back in the game.

REMARK 4.2. There exists a constant C such that for any word $w \in A^*$

$$K(w) \leq |w| \log_2 |A| + C.$$

Actually, there are better estimates which will be discussed elsewhere.

Now we define Kolmogorov complexity of an element of a free group $F = F(X)$ with a basis X . Let $X^{-1} = \{x^{-1} \mid x \in X\}$ and $A = X \cup X^{-1}$. For an element $f \in F$ denote by w_f the unique reduced word in the alphabet A which represents f .

Now the Kolmogorov complexity $K(f, X)$ of f , with respect to the basis X , is defined as

$$K(f) = K(w_f).$$

It is easy to see that for different bases X and Y of F , the corresponding Kolmogorov complexities are equivalent up to some additive constants, i.e., there are positive integers C_1 and C_2 such that for any $f \in F$,

$$K(f, Y) - C_1 \leq K(f, X) \leq K(f, Y) + C_2.$$

This allows us to fix an arbitrary basis of the free group F and consider all the Kolmogorov complexities with respect to this particular basis.

5. Kolmogorov complexity functions on finitely generated groups

Let G be a group generated by a finite set X . There are several ways of introducing Kolmogorov complexity on G .

Method I. Let $F(X)$ be a free group on X and let $\eta : F(X) \rightarrow G$ be the canonical epimorphism. For an element $g \in G$ define the Kolmogorov complexity $K(g, X)$ of g with respect to X as follows

$$K(g, X) = \min\{K(w, X) \mid \eta(w) = g\},$$

i.e., the Kolmogorov complexity of $g \in G$ is the minimum of Kolmogorov complexities of representatives of g with respect to X .

As we have already seen, $K(g, X)$ can be estimated from above by the geodesic length of g in the Cayley graph of G with respect to the set X of generators. It is extremely difficult to deal with this type of complexity if the set of such geodesics is itself very complex. In this event, it might be useful to consider some special normal forms of elements. For example, this is the case for braid groups with respect to the set of Artin generators.

Method II. Suppose the group G has a set of normal forms V , i.e., there exists a subset $V \subset F$ such that $\eta|_V$ is one-to-one. Then one can define Kolmogorov complexity of $g \in G$ with respect to V as

$$K(g, V) = K(\eta^{-1}|_V(g)).$$

The following method provides an *average* Kolmogorov complexity with respect to a given measure on F .

Method III. Let $\eta : F \rightarrow G$ be as above. Let $d : \mathcal{N} \rightarrow R$ be a probability on \mathcal{N} and $c : F \rightarrow \mathcal{N}$ a Kolmogorov complexity function on F . As we have discussed above, there exists a probability measure $\mu = \mu_{c,d}$ on the group F . Define an *average* Kolmogorov complexity of $g \in G$ with respect to d , c , and X as follows:

$$KA(g, d, c, X) = \frac{\sum_{w \in \eta^{-1}(g)} c(w) \mu_{c,d}(w)}{\sum_{w \in \eta^{-1}(g)} \mu_{c,d}(w)}.$$

6. Short elements bias and behaviour at infinity

In this section we discuss how to deal with short elements bias in an infinite group.

Let G be a finitely generated group with a finite set X of generators. For simplicity we will discuss only measures corresponding to the length function l_X on G , but similar arguments can be applied for other complexity functions as well. Let

$$C_n = \{g \in G \mid l_X(g) = n\}, \quad B_n = \{g \in G \mid l_X(g) \leq n\}$$

Let μ be an atomic function on G . Since $\sum \mu(C_k) = 1$, we have $\mu(C_k) \rightarrow 0$ as $k \rightarrow \infty$. Therefore elements of bigger length in a set $S \subseteq G$ contribute less

to $\mu(S)$, i.e., we witness the *short elements bias*. On one hand, this meets our intuitive expectations because, technically, random elements of a very big length are inaccessible to us, e.g., no computer can generate for us a random element of length $> 10^{100}$. On the other hand, it may happen that only a few short elements essentially define the measure of an infinite set.

There are several approaches to deal with the short elements bias.

Method I.

In practical computations with groups, when we wish to evaluate performance of a given algorithm \mathcal{A} , a typical solution to this problem is the following. Choose a sufficiently big random positive integer n (or several of them), generate (pseudo) randomly and uniformly enough elements of length n , and run your algorithm on the produced inputs. The choice of n usually depends on the computer resources and the hardness of the algorithm. Mathematically this can be modelled by the probability distribution μ_{l_X, d_n} with Dirac density d_n . The only problem is the choice of n . Theoretically, to avoid the bias toward short elements, one has to take the limit when $n \rightarrow \infty$. More precisely, let R be a subset of G . Denote by $\rho_n(R)$ the measure of R with respect to Dirac density concentrating at n :

$$\rho_n^{(s)}(R) = \frac{|R \cap C_n|}{|C_n|}.$$

Then the asymptotic behaviour of the set R (with respect to Dirac densities) can be characterized by the following limit (if it exists):

$$\rho^{(s)}(R) = \lim_{n \rightarrow \infty} \rho_n^{(s)}(R)$$

This limit is called the *spherical asymptotic density* of the set R .

Similarly, if we measure R with respect to the disc uniform density function (with respect to the complexity function l_X):

$$\rho_n^{(d)}(R) = \frac{|R \cap B_n|}{|B_n|},$$

and then take the limit (if it exists)

$$\rho^{(d)}(R) = \lim_{n \rightarrow \infty} \rho_n^{(d)}(R)$$

then we get the *disc asymptotic density* of the set R .

In Section 10 we discuss asymptotic densities in detail, here it is worthwhile to mention only that these characteristics are not sensitive enough to distinguish various subsets of groups. For example, all subgroups of infinite index have the same asymptotic density (disc or spherical) equal to 0.

Method II.

Let μ be a probability distribution on G . Then the *mean length* $L_{\mu, X}$ of elements of G with respect to μ and the set X of generators is the expected value of the length function l_X :

$$L_{\mu, X} = \sum_{g \in G} l_X(g) \mu(g).$$

For example, if $G = F(X)$ and a measure $\mu_\lambda = \mu_{l_X, d_\lambda}$ is given on $F(X)$ by the exponential density:

$$d_\lambda(k) = (1 - e^{-\lambda}) e^{-\lambda k}$$

then the mean length L_λ of words in F distributed according to μ_λ is equal to

$$\begin{aligned} L_\lambda &= \sum_{w \in F} |w| \mu(w) = (1 - e^{-\lambda}) \sum_{k=1}^{\infty} k (e^{-\lambda})^k = \\ &= \frac{(1 - e^{-\lambda})}{e^\lambda} \sum_{k=1}^{\infty} k (e^{-\lambda})^{k-1} = \frac{1}{(e^\lambda - 1)e^\lambda}. \end{aligned}$$

Hence $L_\lambda \rightarrow \infty$ when $\lambda \rightarrow 0$. Thus, we have

a family of probabilistic distributions $\{\mu_\lambda\}_\lambda$ with parameter λ such that the mean length L_λ tends to ∞ when the parameter λ approaches 0.

Similar results hold for all other distributions introduced in Section 3 (after renormalizing the parameters).

Now one can measure the behaviour of R at infinity by the following limit (if it exists)

$$\mu_\infty(R) = \lim_{\lambda \rightarrow 0} \mu_\lambda(R).$$

A study of limits of this type was initiated in [3].

Note that if $\{\mu_k\}_k$ is the Dirac parametric family of distributions, then

$$\mu_\infty(R) = \rho^{(s)}(R),$$

and if $\{\mu_k\}_k$ is the parametric family of disc uniform distributions, then

$$\mu_\infty(R) = \rho^{(d)}(R).$$

7. Degrees of polynomial growth “on average”

Let $c : F_n \rightarrow \mathbb{R}$ be a complexity function and μ the measure moderated by the Cauchy distribution

$$d(k) = \frac{6}{\pi^2} \cdot \frac{1}{k^2}.$$

The advantage of this distribution is that it allows to measure degrees of polynomial growth of functions on F_n “on average” in the following sense.

Let $f : F_n \rightarrow \mathbb{R}$ be a non-negative real valued function. We say that f has polynomial growth of degree $\alpha \geq 0$ if α is the greatest lower bound of the set of real positive numbers β such that the mean value of $\frac{f(w)}{c(w)^{\beta-1}}$ is finite, that is,

$$(7.1) \quad \alpha = \inf \left\{ \beta \left| \sum_{w \in F_n} \frac{f(w)}{c(w)^{\beta-1}} \mu_{c,d}(w) \text{ converges} \right. \right\}.$$

It follows immediately from the construction of our measure that the function $c(w)^m$ has growth of degree m . (Just recall that the series $\sum \frac{1}{n^{1+\epsilon}}$ converges for all $\epsilon > 0$, while the harmonic series $\sum \frac{1}{n}$ diverges.)

In particular, if $f(x)$ is the running time of some algorithm with input x , this definition allows us to make meaningful statements like “the algorithm works in cubic time on average”.

Now we are going to generalize this situation and try to find sufficient conditions to define the degrees of growth of functions on an arbitrary infinite factor group of F_n .

Let $G = F_n/R$ be an infinite factor group of the free group F_n and $\eta : F_n \rightarrow G$ the natural homomorphism. We shall list some natural conditions for the complexity function c on F_n and the moderating probability distribution d which allow us to define degrees of the average growth of functions on G .

(D1) (*Existence of a complexity function on G .*) The mean complexity

$$\bar{c}(\bar{g}) = \frac{\sum_{w \in \bar{g}} c(w) \mu_{c,d}(w)}{\sum_{w \in \bar{g}} \mu_{c,d}(w)}$$

is finite for every $\bar{g} \in G$.

(D2) (*Existence of degrees.*) There exists a positive number τ such that the series

$$\sum_{\bar{g} \in G} \bar{c}(\bar{g})^a \bar{\mu}(\bar{g})$$

converges for $a < \tau$ and diverges for $a > \tau$; $\bar{\mu}$ here is the measure on G induced by the measure $\mu_{c,d}$ on F_n .

If these conditions are satisfied, we can define the degree of growth of an arbitrary nonnegative real valued function $f(\bar{g})$ on G as

$$(7.2) \quad (\text{degree of growth of } f) = \inf \left\{ \beta \left| \sum_{\bar{g} \in G} \frac{f(\bar{g})}{\bar{c}(\bar{g})^{\beta-\tau}} \bar{\mu}(\bar{g}) \text{ converges} \right. \right\}.$$

Now we at least have the (easy to check) property that the degree of growth of the function $\bar{c}(\bar{g})^m$ is m .

Note that not every moderating probability distribution d on $\mathbb{N} \cup \{0\}$ is suitable for defining degrees of polynomial growth. For example, if we take in the definition of the degrees of growth on the free group F_n , the exponential distribution

$$d(k) = (1 - e^{-\lambda}) \cdot e^{-\lambda k},$$

we note that the series

$$\sum_{x \in F_n} c(x)^a \mu_{c,d}(x)$$

converges for all a .

QUESTION 7.1. *Can one find a moderating probability distribution d such that the conditions D1 and D2 are satisfied for every factor group $G = F_n/R$ of infinite index and the measure $\bar{\mu}$ on G induced from $\mu_{c,d}$?*

The Cauchy distribution $d(k) = \frac{6}{\pi^2} \cdot \frac{1}{k^2}$ is still on the list of candidates for the affirmative answer.

We need to warn that the degree of growth of a function f on G is not necessarily equal to the degree of growth of its lift $f \circ \eta : F_n \rightarrow \mathbb{R}$. It might happen that, for certain problems, it is much more convenient to work in a free group than in its factor group G and evaluate the degrees of growth of the lifted function $f \circ \eta$ instead of those of f . Therefore general results concerning relations between degrees of growth on F_n and $G = F_n/R$ would be rather interesting.

8. Measures generated by random walks

8.1. Random walks. An interesting and, in some cases, easier to analyze class of measures is related to random walks on Cayley graphs of groups. From an algorithmic point of view, the most natural way to produce a random element in a finitely generated group is to first make a random word on the generators, and then apply relations. This is, in disguise, a random walk on the Cayley graph of a given group. This becomes especially relevant when hardware random numbers generators are used to produce random words.

Let us look at this basic procedure in more detail.

Let F_n be a free group on free generators x_1, \dots, x_n . We can associate with it a free monoid M_n with the generators $x_1, X_1, \dots, x_n, X_n$ and the natural homomorphism $\pi : M_n \rightarrow F_n$ which sends x_i to x_i and X_i to x_i^{-1} . A random walk of length l on the Cayley tree of F_n which starts at the identity 1 is naturally described by a word of length l in M_n .

In essence, we take M_n , not F_n , as the ambient algebraic structure, and introduce measures and complexity functions on M_n rather than on F_n . There is a compelling evidence that, in at least some problems, it might be convenient to work in the ambient free monoid M_n . For example, it appears that physicists prefer to use the random walk approach in their study of statistics of braids, knots and heaps, the latter being closely related to *locally free groups*

$$\mathcal{LF}_n = \langle f_1, \dots, f_n \mid [f_i, f_j] = 1 \text{ for } |i - j| > 1 \rangle$$

(see e.g. [6, 7, 8, 24]). In any case, the physical process of the accumulation of soot (in the 2-dimensional case) is most naturally modeled by random walks on the monoid of positive words in \mathcal{LF}_n .

Let $d : \mathbb{N} \cup \{0\} \rightarrow \mathbb{R}$ be a moderating probability distribution. Following the analogy with our constructions for a free group, we introduce an atomic probability measure $\tilde{\mu}$ on M_n by assigning equal probabilities to words of equal complexity and the total measure $d(k)$ to the set of words of complexity k . This can be interpreted as running random walks on F_n of random complexities k distributed with the probability density $d(k)$. The probability for a random walk to stop at the element $x \in F_n$ defines a measure $\mu(x)$ on F_n . Obviously,

$$\mu(x) = \sum_{\pi(w)=x} \tilde{\mu}(w).$$

8.2. How is this new measure related to Kolmogorov complexity measures? The measure that we have just defined should have properties very close to Kolmogorov complexity measures described in Section 4. The word $x = \pi(w)$ is obtained from a word w by cancelling all adjacent pairs of elements of the form $x_i X_i$, which amounts to running a certain Turing machine on the input word w . Therefore, in view of the previous discussion, the Kolmogorov complexity $c(x)$ of x differs from the Kolmogorov complexity $c(w)$ of w by at most an additive constant:

$$c(x) \leq c(w) + C.$$

Since for most words of a fixed big length l , Kolmogorov complexity is close to the length of the word, we should expect roughly the same asymptotic behaviour from a random walk measure as we do from a measure associated with Kolmogorov complexity.

8.3. Comparing the length of a random walk with the geodesic length.

In a simple case, where the complexity function on M_n is just the usual length function $l(w)$, we can similarly compare its behaviour with the behaviour of the geodesic length $l = l_{\text{geod}}(x)$ of the end point $x = \pi(w)$ of the walk on the Cayley tree $\Gamma(F_n)$ of F_n , described by the word w .

It is easy to see that the function $x \mapsto l_{\text{geod}}(x)$ maps a random walk on $\Gamma(F_n)$ to a non-symmetric random walk \mathcal{W}_+ on the set $\mathbb{N} \cup \{0\}$ of nonnegative integers with reflection at 0. In this new walk, we make steps of length 1; we move from the point $l = 0$ to the right with probability 1, and, from any other point $l \neq 0$, we move to the right with the probability $p = \frac{2n-1}{2n}$ and to the left with the probability $q = \frac{1}{2n}$. Obviously, the mean value of l is at least the mean value of l for a random walk \mathcal{W} on \mathbb{Z} without reflection at 0; in this walk we start at 0 and move by 1 to the right with the probability p and by 1 to the left with the probability q . In \mathcal{W} , we make m moves to the right with the probability $\binom{k}{m} \cdot p^m \cdot q^{k-m}$ and end up at the point $l' = m - (k - m) = 2m - k$. Thus, the random variable l' is a linear transformation of the random variable m distributed according to the binomial distribution. Since the expectation $E(m) = pk$, we deduce that $E(l') = 2pk - k = \frac{n-1}{n}k$.

Therefore, for the random walk \mathcal{W}_+ , the expected value of l is bounded from below by $\frac{n-1}{n}k = E(l') \leq E(l)$. The upper bound $E(l) \leq k$ is obvious. Thus, the expected geodesic length $E(l_{\text{geod}}(x))$ of an element $x \in F_n$ produced by a random walk of length k is estimated as

$$\frac{n-1}{n}k \leq E(l_{\text{geod}}(x)) \leq k.$$

9. Behaviour of the induced measures on finite factor groups

In this section we try to establish possible criteria to evaluate how “natural” a given measure is, i.e., how it matches our expectations of what the probability of hitting particular sets should be. In general, these expectations may, of course, vary from individual to individual, but we have some common grounds, at least, in the case of finite sets. So, our idea is to set up some tests to compare a given measure μ on a free group $F = F_n$ with the induced measures on finite quotients of F . Most people will probably agree that, for example, the probability for a randomly chosen element of F to have even length should be about $1/2$. More generally, it is natural to expect that a subgroup $H < F$ of an index m would have the measure (approximately) equal to $\frac{1}{m}$. Unfortunately, this is not the case if $\mu(1) > 0$, indeed, if $m \gg \frac{1}{\mu(1)}$ then $\mu(H) \geq \mu(1) \gg \frac{1}{m}$.

Moreover, most people working with probabilities on finite groups are likely to prefer measures which are well behaved with respect to taking “big” finite factors F_n/R , for example, measures which yield reasonable bounds for the total variance distance

$$(9.1) \quad \frac{1}{2} \sum_{\bar{g} \in F_n/R} \left| \mu(\bar{g}) - \frac{1}{|F_n : R|} \right|$$

of the induced distribution from the uniform distribution on F_n/R . Again, this natural condition cannot be satisfied basically for the same reason, namely, the value of (9.1) is bounded from below by $\frac{1}{2}|\mu(1) - (1/m)|$, where $m = |F_n : R|$, and does not converge to 0 as $m \rightarrow \infty$.

This is a typical example of an unexcusable dependance of a measure on short elements. This is one of the many reasons to believe in the following (maybe controversial) metamathematical thesis:

There is no particular atomic measure on an infinite group which would meet our expectations of sizes of particular sets in the group

A possible practical outcome of this thesis is either to consider a whole family of parametric measures on a group instead of a fixed one, or to adjust our criteria to allow a margin of an error of approximation. The first approach was developed to some extent in [3], here we make an attempt to consider the second one.

One may wish to exclude anomalously big probabilities of short elements by taking the measure of an element gR in a finite factor group F_n/R to be the renormalized measure of the set of “large” elements in gR :

$$(9.2) \quad \bar{\mu}_l(gR) = \frac{\mu((F_n \setminus B_l) \cap gR)}{\mu(F_n \setminus B_l)},$$

where B_l is the ball of radius l centered at 1. Anyway, it is only natural to assume that, when assessing the average case complexity of algorithmic problems of practical interest, we are working with words of sufficiently large size; the bias towards short elements can be safely ignored. A measure μ can be accepted as “good” if, for values of l much smaller than m ,

$$(9.3) \quad \frac{1}{2} \sum_{\bar{g} \in F_n/R} \left| \bar{\mu}_l(\bar{g}) - \frac{1}{|F_n : R|} \right| < \frac{1}{e},$$

or is bounded by some other reasonable constant, or decreases exponentially with the growth of l :

$$(9.4) \quad \frac{1}{2} \sum_{\bar{g} \in F_n/R} \left| \bar{\mu}_l(\bar{g}) - \frac{1}{|F_n : R|} \right| = o(e^{-cl}).$$

The reader probably feels already at this point that we are leaning towards the classical concept of a random walk on a group. Taking images of “sufficiently long” elements means allowing a sufficiently long random walk on the finite group F_n/R . It is reasonable to take the mixing time of the random walk on the factor group F_n/R with respect to the generators x_1R, \dots, x_nR for the characteristic word length l in the criterion (9.3). Recall that the mixing time is defined as the minimum l_0 such that

$$(9.5) \quad \|P_{l_0} - U\| = \frac{1}{2} \sum_{\bar{g} \in F_n/R} \left| P_{l_0}(\bar{g}) - \frac{1}{|F_n : R|} \right| < \frac{1}{e},$$

where $P_l(\bar{g})$ is the probability for a random walk of length l to end up at the element \bar{g} , and U is the uniform distribution on F_n/R . From the mixing time on, a random walk distribution converges to the uniform distribution exponentially fast:

$$(9.6) \quad \|P_{kl_0} - U\| = \frac{1}{2} \sum_{\bar{g} \in F_n/R} \left| P_{kl_0}(\bar{g}) - \frac{1}{|F_n : R|} \right| = o(e^{-ck}).$$

Therefore, we can consider an alternative criterion for good behaviour of the measure on finite factor groups:

(C1*) For every finite factor group $G = F_n/R$ there exists a number l_0 such that

$$\frac{1}{2} \sum_{\bar{g} \in F_n/R} \left| \bar{\mu}_{kl_0}(\bar{g}) - \frac{1}{|F_n : R|} \right| = o(e^{-k}).$$

Of course, the value of l_0 (“the mixing time”) is all important. One should expect from a ‘good’ measure on F_n that it is approximately the same as the mixing time of a random walk on F_n/R . It is worth mentioning here, that, by a result by Pak [20], a random walk on a finite group G with respect to a random generating set of size $O(\log |G|)$ mixes under $O(\log |G|)$ steps.

It is relatively easy to see that our criterion (C1*) is met by a wide class of measures associated with the length function on F_n .

THEOREM 9.1. *If the moderating distribution $d(k)$ satisfies a rather natural condition $d(k) > 0$ for infinitely many values of k then, for every finite factor group $G = F_n/R$, the induced measure $\bar{\mu}_l$ on G satisfies the condition (C1*).*

9.1. Proof of Theorem 9.1. Let $|G| = m$. Every probability distribution on G is a vector p_1, \dots, p_m of non-negative real numbers subject to the condition $p_1 + \dots + p_m = 1$. Thus, the set of all probability distributions on G is the convex hull Δ of the distributions E_g concentrated at $g \in G$, i.e., $E_g(h) = 1$ if $h = g$ and 0 otherwise. We introduce on Δ the total variance metric

$$\|P - Q\| = \frac{1}{2} \sum_{g \in G} |P(g) - Q(g)|.$$

A step of a random walk induces an affine transformation $\tau : \mathbb{R}^m \rightarrow \mathbb{R}^m$ by the rule

$$\tau : E_g \mapsto \frac{1}{2n} \sum_{h \text{ adjacent to } g} E_h,$$

where the adjacency is considered in the Cayley graph of G .

Since all vertices of the Cayley graph of G have the same degree, τ fixes the uniform distribution $U = (1/m, \dots, 1/m)$. By somewhat abusing the notation, we can move the origin of the coordinate system in \mathbb{R}^m to the point U . It will be convenient to restrict the action of τ to the subspace \mathbb{R}^{m-1} spanned in \mathbb{R}^m by the polytope Δ . Then the distance $\|X - U\|$ becomes a norm on \mathbb{R}^{m-1} (which we denote by $\|X\|$; hopefully, this will not cause a confusion), and τ becomes a linear operator on \mathbb{R}^{m-1} . Note that the norms $\|\tau^k(E_g)\|$ of vertices of the convex polytope $\tau^k(\Delta)$ are all equal. Since τ maps the vertices E_g of Δ to points of Δ , it does the same to the vertices of $\tau^k(\Delta)$. As a result, we have the following monotonicity property:

$$\|\tau^{k+1}(E_g)\| \leq \|\tau^k(E_g)\|.$$

We can use again the property that τ maps the vertices E_g of the convex polytope Δ to prove that $\|\tau(E_g)\|_E < \|E_g\|_E$ for all $g \in G$, where $\|\cdot\|_E$ stands for the standard Euclidean norm on \mathbb{R}^{m-1} . It follows that

$$\|\tau\|_E = \max_{X \in \Delta, X \neq 0} \frac{\|\tau(X)\|_E}{\|X\|_E} < 1,$$

hence $\|\tau^k(X)\|_E \rightarrow 0$ as $k \rightarrow \infty$ for every distribution X . Moreover, $\|\tau^k(X)\|_E$ decreases exponentially: $\|\tau^k(X)\|_E = o(c^k)$. Since any two norms on a finite dimensional space are equivalent, we have

$$\frac{1}{C} \|X\|_E < \|X\| < C \|X\|_E$$

for some constant C , and it follows that $\|\tau^k(X)\| = o(c^k)$.

We have, in our new notation,

$$\begin{aligned} \frac{1}{2} \sum_{g \in G} \left| \bar{\mu}_l(g) - \frac{1}{m} \right| &= \|\bar{\mu}_l\| = \left\| \frac{1}{\sum_{k \geq l} d(k)} \sum_{k \geq l} d(k) \tau^k(E_1) \right\| \\ &= \frac{1}{\sum_{k \geq l} d(k)} \left\| \sum_{k \geq l} d(k) \tau^k(E_1) \right\| \leq \frac{1}{\sum_{k \geq l} d(k)} \left\| \sum_{k \geq l} d(k) \tau^l(E_1) \right\| \\ &= \|\tau^l(E_1)\| \cdot \frac{\sum_{k \geq l} d(k)}{\sum_{k \geq l} d(k)} = \|\tau^l(E_1)\|. \end{aligned}$$

We see that the probabilistic distribution on G produced by a random walk of random length $\geq l$ converges to the uniform distribution as fast as the probability distribution after l steps of the usual random walk does. In particular, this proves that the measure $\bar{\mu}_l$ on G satisfies the condition (C1*).

10. The growth function and asymptotic density

In this section, we discuss an approach to analyze the asymptotic behaviour of sets in a group via asymptotic densities introduced in Section 6.

Let G be a group with a complexity function $c: G \rightarrow \mathcal{N}$ (for example, a group generated by a finite set X with the length function l_X).

A *pseudo-measure* on G is a real-valued nonnegative additive function defined on some subsets of G . The pseudo-measure μ is called *atomic* if $\mu(S)$ is defined for any finite subset S of G . Let C_k and B_k be, respectively, the sphere and the ball of radius k in G with respect to the complexity c .

For a set $R \subseteq F$, we define its *spherical asymptotic density* with respect to μ as the following limit (if it exists):

$$\rho_\mu^{(s)}(R) = \lim_{k \rightarrow \infty} \rho_k^{(s)}(R),$$

where

$$\rho_k^{(s)}(R) = \frac{\mu(R \cap C_k)}{\mu(C_k)}.$$

Similarly, we define *disc asymptotic density* of R as the limit (if it exists):

$$\rho_\mu^{(d)}(R) = \lim_{k \rightarrow \infty} \rho_k^{(d)}(R),$$

where

$$\rho_k^{(d)}(R) = \frac{\mu(R \cap B_k)}{\mu(B_k)}.$$

One can also define the density functions above using lim sup rather than lim.

For example, if μ is the cardinality function, i.e., $\mu(A) = |A|$, then we obtain the standard asymptotic density functions $\rho^{(c)}$ and $\rho^{(d)}$ on G .

Moreover, if μ is c -invariant, i.e., $\mu(u) = \mu(v)$ provided $c(u) = c(v)$, then the spherical asymptotic density with respect to μ is equal to the standard spherical asymptotic density:

$$s\rho_\mu = s\rho.$$

LEMMA 10.1. *For any atomic pseudo-measure μ on G , the asymptotic densities $\rho^{(c)}$ and $\rho^{(d)}$ are also atomic pseudo-measures on G .*

Proof is obvious.

LEMMA 10.2. *Let μ be a pseudo-measure on G . Suppose that*

$$\lim_{k \rightarrow \infty} \mu(B_k) = \infty.$$

Then, for any subset $R \subseteq G$, if the spherical asymptotic density $\rho_\mu^{(c)}(R)$ exists, then the disc asymptotic density $\rho_\mu^{(d)}(R)$ exists, too, and

$$\rho_\mu^{(c)}(R) = \rho_\mu^{(d)}(R).$$

Proof. Let $x_k = \mu(R \cap B_k)$ and $y_k = \mu(B_k)$. Then $y_k < y_{k+1}$ and $\lim y_k = \infty$. By Stolz's theorem

$$\lim_{k \rightarrow \infty} \frac{x_k}{y_k} = \lim_{k \rightarrow \infty} \frac{x_k - x_{k-1}}{y_k - y_{k-1}}.$$

Hence

$$\rho_\mu^{(d)}(R) = \lim_{k \rightarrow \infty} \frac{\mu(R \cap S_k)}{\mu(S_k)} = \rho_\mu^{(s)}(R),$$

as claimed.

In view of this result we will refer to the standard (spherical or disc) densities ρ .

Asymptotic densities provide a useful, though very coarse, tool to describe behaviour of sets at infinity. Furthermore, there are very natural subsets which are sadly unmeasurable with respect to ρ . To see this, consider the set E_n of words of even length in a free group F_n of rank n . Then $\rho(E_n)$ is easily seen to be undefined. A way around this problem (involving generalized summation methods for series) is discussed in [3].

Moreover, the following well-known result shows that that ρ is not sufficiently sensitive.

THEOREM 10.3. (Woess [27]) *If N is a normal subgroup of F_n , $n \geq 2$, of infinite index, then $\rho(N) = 0$.*

Another disappointment is offered by the following result. As usual, we call an element $u \in F_n$ *primitive* if it is part of a free basis of F_n , or, equivalently, if $\alpha(u) = x_1$ for some $\alpha \in \text{Aut}(F_n)$.

THEOREM 10.4. *Let F_n be the free group of a finite rank $n \geq 2$. Then:*

$$\rho(\text{Pr}_n) = 0,$$

where Pr_n is the set of all primitive elements of the group F_n . More precisely, if $P(n, k)$ is the number of primitive elements of length k in F_n , $n \geq 3$, then for some constants c_1, c_2 , one has

$$c_1 \cdot (2n - 3)^k \leq P(n, k) \leq c_2 \cdot (2n - 2)^k.$$

We see that the asymptotic density ρ is not sensitive enough in measuring sets in F_n . It would be very interesting therefore to check whether probabilistic results of, say, [1], [5], [19], that are based on the asymptotic density ρ , will hold upon replacing ρ with a more adequate measuring tool.

10.1. Proof of Theorem 10.4. Our proof is based on the fact that the Whitehead graph of any primitive element of length > 2 has either an isolated edge or a cut vertex, i.e., a vertex that, having been removed from the graph together with all incident edges, increases the number of connected components of the graph. Recall that the Whitehead graph $Wh(u)$ of a word u is obtained as follows. The vertices of this graph correspond to the elements of the free generating set X and their inverses. If the word u has a subword $x_i x_j$, then there is an edge in $Wh(u)$ that connects the vertex x_i to the vertex x_j^{-1} ; if u has a subword $x_i x_j^{-1}$, then there is an edge that connects x_i to x_j , etc. We note that usually, there is one more edge (the external edge) included in the definition of the Whitehead graph: this is the edge that connects the vertex corresponding to the last letter of u , to the vertex corresponding to the inverse of the first letter.

Assume first that the Whitehead graph of u has a cut vertex. We are going to show that the number of elements u of length k with this property is no bigger than $C \cdot (2n - 2)^{k-1}$, where $C = C(n)$ is a constant.

Let $Wh(u)$ be a disjoint union of two graphs, Γ_1 and Γ_2 , complemented by a (cut) vertex A together with all incident edges. Let $n_1 \geq 1$ and $n_2 \geq 1$ be the number of vertices in Γ_1 and Γ_2 , respectively. Then, in particular, $n_1 + n_2 = 2n - 1$. Let $m = \min(n_1, n_2)$.

The first letter of u can be any of the $2n$ possible ones. For the following letter however we have no more than $2n - m$ possibilities since, for example, if the first letter, call it x_i , corresponds to a vertex from Γ_1 , then the following letter, call it x_j , cannot be such that the vertex corresponding to x_j^{-1} belongs to Γ_2 , because otherwise, there would be an edge in $Wh(u)$ that connects Γ_1 to Γ_2 directly, not through A , i.e., A would not be a cut vertex.

Thus, there are only $2n - n_2 \leq 2n - m$ possibilities for the following letter in u . The same argument applies to every letter in u , starting with the second one; therefore, the total number of possibilities (corresponding to a particular choice of n_1 and n_2) is no bigger than $C \cdot (2n - m)^{k-1}$, where $C = C(n)$ is a constant.

Now consider two cases:

(i) $m \geq 2$.

In this case, the number in question is bounded by $C \cdot (2n - 2)^{k-1}$.

(ii) $m = 1$.

In this case, one of the graphs, say, Γ_2 , consists of a single vertex (call it x_1 for notational convenience) connected only to the cut vertex (call it x_2); in particular, the vertex x_1 is a terminal vertex of the graph $Wh(u)$, and, whenever the letter x_1 occurs in u , it is followed by x_2^{-1} . Let $q \geq 1$ be the number of occurrences of x_1 in u .

Apply the automorphism $\phi : x_1 \mapsto x_1 x_2, x_i \mapsto x_i, i \geq 2$, to the element u . Then $|\phi(u)| = |u| - q < |u|$. Now $\phi(u)$ is a primitive element, too; hence the whole argument above is applicable to $\phi(u)$. In particular, if, in the notation above, $m \geq 2$ for this element $\phi(u)$, then, as we have just proved, the number of those elements is bounded by $C \cdot (2n - 2)^{k-1-q}$ for some $C = C(n)$. This number is also equal to the number of elements u of the type we are considering now (for a particular q) because of the one-to-one correspondence between elements u and $\phi(u)$.

If $m = 1$ for the element $\phi(u)$, then we use the same trick again, until we get to a primitive element with $m \geq 2$. In any case, the number of primitive

elements of length k , with $m = 1$, and with $q \geq 1$ occurrences of x_1 , is bounded by $C \cdot (2n - 2)^{k-1-q}$ for some $C = C(n)$.

Now we have to sum up for all possible values of q . Note that q cannot be equal to k since x_1^k is not a primitive element; also, q cannot be equal to $k - 1$ since in the Whitehead graph of $x_1^{k-1}x_2$, the vertex corresponding to x_1 is not a terminal vertex. Hence, we have

$$\sum_{q=1}^{k-2} C \cdot (2n - 2)^{k-1-q} = C \cdot \frac{(2n - 2)^{k-1} - 1}{2n - 3} \leq C \cdot (2n - 2)^{k-1}.$$

Finally, we have to multiply this number by the number of ways we can choose two vertices (terminal and cut) out of $2n$, i.e., by $(2n - 1)n$, but this does not change the type of the bound. Therefore, we get here the same bound as we got in the case $m \geq 2$.

Thus, summing up for all possible values of $n_1 \geq 1$ and $n_2 \geq 1$ such that $n_1 + n_2 = 2n - 1$, we see that the total number of possibilities in (i) and (ii) is bounded by $C \cdot (2n - 2)^k$ for some $C = C(n)$.

Finally, we address the remaining case, where the Whitehead graph of u has an isolated edge. In that case, some cyclic permutation of u must be of the form $x_i^{\pm 1}x_j^{\pm 1}u_1$, where u_1 does not depend on x_i, x_j , and j does not have to be different from i . The number of elements with this property is easily seen to be bounded by $C \cdot k \cdot (2n - 3)^{k-1}$ for some constant $C = C(n)$.

Therefore, the ratio of the number of primitive elements of length k to the number of all elements of length k is no more than $C \cdot \frac{(2n-2)^k}{2n(2n-1)^{k-1}} = C' \cdot \left(\frac{2n-2}{2n-1}\right)^k$, where $C' = C'(n)$ is a constant. This ratio obviously tends to 0, and, moreover, well-known properties of a geometric series now imply that the ratio of the number of primitive elements of length $\leq k$ to the number of all elements of length $\leq k$ tends to 0, too.

Finally, we note that the lower bound $c_1 \cdot (2n - 3)^k \leq P(n, k)$ is obvious because every element of the form $x_1 \cdot u(x_2, \dots, x_{n-1})$ is primitive. \square

Just to complete the picture, we also mention here the bounds for the number of primitive elements of length k in F_2 :

PROPOSITION 10.5. ([18]) *The number of primitive elements of length k in the group F_2 is:*

- (a) *more than $\frac{4}{\sqrt{3}} \cdot (\sqrt{3})^k$ if k is odd.*
- (b) *more than $\frac{4}{3} \cdot (\sqrt{3})^k$ if k is even.*

Informally speaking, “most” primitive elements in F_2 are conjugates of primitive elements of smaller length. This is not the case in F_n for $n > 2$, where “most” primitive elements are of the form $u \cdot x_i^{\pm 1} \cdot v$, where u, v are arbitrary elements that do not depend on x_i .

10.2. The rate of convergence of the asymptotic density. Let S be a subset of a free group F_n of rank $n \geq 2$. As we have mentioned in the Introduction, the growth rate of the set S is defined as the limit

$$\gamma(S) = \limsup_{k \rightarrow \infty} \sqrt[k]{\rho_k(S)},$$

where

$$\rho_k(S) = \frac{|S \cap B_k|}{|B_k|}$$

are the disc relative frequencies of S . The growth rate $\gamma(S)$ is gauging the speed of convergence to zero of the sequence $\rho_k(S)$. Indeed, the standard results from calculus show that if $\gamma(S) < 1$, then $\rho(S) = 0$, and, moreover, the sequence $\rho_k(S)$ converges to 0 exponentially fast.

A classical theorem by Grigorchuk [9] states that if $N \triangleleft F_n$ and F_n/N is not an amenable group, then $\gamma(N) < 1$. This gives us many easy examples of normal subgroups N with the exponential speed of convergence of the asymptotic density. For example, this happens every time when the factor group F_n/N contains a non-abelian free group.

It would be interesting to have a look at the other end of the spectrum and estimate the speed of convergence of the sequence $\rho_k(N)$ for an obviously “big” subgroup $N \triangleleft F_n$. The following result is one of the very few instances where we have concrete information:

THEOREM 10.6. (Sharp [21]) *If $n \geq 2$, then the spherical relative frequencies*

$$\rho_k^{(s)} = \frac{|[F_n, F_n] \cap S_k|}{|S_k|}$$

of words of length k from the derived subgroup $[F_n, F_n]$ of the free group F_n asymptotically behave as

$$\rho_k^{(s)} \sim \begin{cases} 0 & \text{if } k \text{ is odd,} \\ \frac{C}{k^{n/2}} & \text{if } k \text{ is even.} \end{cases}$$

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